OMRON

Specifications

600 mm

Reach

Omron Adept eCobra 600









eCobra is the newest family of 4-axis SCARA robots from Omron Adept. The eCobra 600 features a 600-mm reach, and is available in three performance tiers – eCobra Lite, eCobra Standard, and eCobra Pro – each designed to address different application complexity and throughput requirements. With all controls fully embedded into the robot, eCobra robots offer a compact system footprint, saving valuable floor space while minimizing installation costs and complexity. Adept eCobra robots provide maximum value by ensuring users only pay for the level of performance their application needs. All eCobra 600 robots share a common hardware platform, with performance and price determined by a software license. This unique family ensures that users receive the highest quality, most durable robots at every performance level.

Product Features

- · Three performance levels (Lite, Standard, and Pro) based on a common hardware platform
- · Upgrade performance with a software license download
- are included in Standard and Proper formance tiers
- Adept ACE™ software manages robots, conveyors, feeders, and device I/O assignment through a single user-friendlyPC-based interface

Product Benefits

- All amplifiers and controls are fully embedded into -> Maximize valuable floor space and reduce installation costs (cables, control cabinets, labor, etc.)
 - -> Maximize value by only paying for the per formance required for the application, without sacrificing hardware quality
 - -> Extend robot life with easy re-deployment for any appli cation with a simple software upgrade
 - Advanced features such as direct PLC programming -> Minimize training and deployment time using familiar ladder logic pro-gramming languages of existing PLC (IEC 61131-3)
 - -> Minimize system deployment and testing time; no lengthyoverly complicated programming. Includes a powerful 3D emulator that allows complete system configuration and testing in a virtual environment

Payload Max.	5.5 kg		
Adept Cycle (in mm 25/305/2	5)		
See Table on Back			
Downward Push Force (No Lo	ad) 30 kgf – maximum		
Moment of Inertia			
Joint 4 (max)	450 kg-cm ² (150 lb-in ²)		
Joint Ranges			
Joint 1	± 105°		
Joint 2	± 157.5°		
Joint 3	210 mm		
Joint 4	± 360°		
Joint Speeds			
Joint 1	386°/sec		
Joint 2	720°/sec		
Joint 3	1100 mm/sec		
Joint 4	1200°/sec		
Robot Brakes			
Joints 1, 2, and 4	Dynamic		
Joint 3	Electric		
Repeatability			
XY	± 0.017 mm		
Z	± 0.003 mm		
Theta	± 0.019°		
Pass-Through Connections			
Electrical	24 (12 twisted pairs)		
Pneumatic	6 mm (x2) 4 mm (x3)		

Environmental Requirements	

Optional Solenoid

Ambient Emperature 5 - 40 °C **Humidity Range** 5 - 90 % (non-condensing)

12 inputs, 8 outputs

4 outputs

41 kg

Power Requirements

24 VDC: 6 A

DeviceNet Digital I/O Channels

eAIB:

W eight

200 - 240 V AC: 10 A, single-phase

CE Compliant

OMRON ADEPT e COBRA 600

The Adept eCobra 600 system includes the following:

- · Adept eCobra 600 robot with eAIB (Amplifiers in Base)
- Software performance license for Lite, Standard, or Pro configuration
- · Front panel with E-Stop and cabling

eCobra License Features:

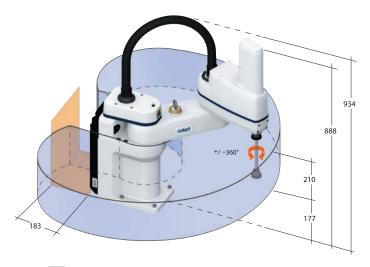
 Adept ACE[™] software – an integrated, point-and-click development environment for Adept's entire product portfolio of robots and controls

Options and Peripherals:

- SmartVision MX industrial PC with AdeptSight™ vision guidance software
- GigE Power over Ethernet and USB 3.0 cameras
- · Cleanroom ISO 4 (class 10) option
- Enhanced dust/water protection (IP65)
- · T20 manual control pendant
- SmartController EX

Feature	P	Performance Tier		
	eCobra Lite	eCobra Standard	eCobra Pro	External Controller
Price (call for details)	Low	Reduced	Full	Optional
Adept cycle (25-305-25mm) time with 2 kg paylod at 20 °C (s)	0.66 Burst 0.66 Sustained	0.55 Burst 0.55 sustained	0.39 Burst 0.45 Sustained	Tier Dependent
Adeptsight Vision support	No	Yes	Yes	Yes
Maximum I/O (Input/Output) supported	12/12	44/44	76/76	999/999
Standard Integrated I/O (Input/Output)	12/12	12/12	12/12	12/8 additional
Optional I/O Blox supported (8/8 each)	0	4	8	Tier Dependent
Optional sDIO support (32/32 each - firewire)	No	No	No	16
Support for DeviceNet	No	No	No	Yes
Warranty (parts/labor)	2/1 yr	2/1 yr	2/1 yr	2/1 yr
CPU performance available	mid	mid	mid	high
Number of user tasks supported	28	28	28	28
Maximum number of Adept robots	1	1	1	4
Maximum number of axes controlled	4	4	4	24
Programming interface	Ethernet	Ethernet	Ethernet	Ethernet
Communication interface	No	No	Ethernet	Ethernet
Control Environment	Adept ACE	Adept ACE Adept PackXpert PLC	Adept ACE Adept PackXpert PLC	Adept ACE Adept PackXpert PLC
Application Programming Interface (API)		ePLC .NET	ePLC .NET	ePLC .NET
Force sensing support		Yes	Yes	Tier Dependent
Active RS232 Serial Communication Ports		1	1	3
ePLC connect (direct IEC 61131-3 programming with existing PLC)		Yes	Yes	Tier Dependent
ePLC I/O (program in eV+, but exchange registers with PLC)			Yes	Yes
Conveyor tracking			Yes	Tier Dependent
Vision on the fly			Yes	Tier Dependent
Active conveyor tracking belt inputs			2	4 additional
Active RS-422/485 serial ports				1

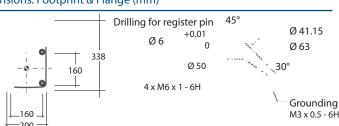
Dimensions: Adept eCobra 600 (mm)



Work Envelope: Radius 600 mm Inner Limit: Radius 163 mm Height: 210 mm

Required clearance to open eAIB Chassis

Dimensions: Footprint & Flange (mm)





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Specifications subject to change without notice.

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