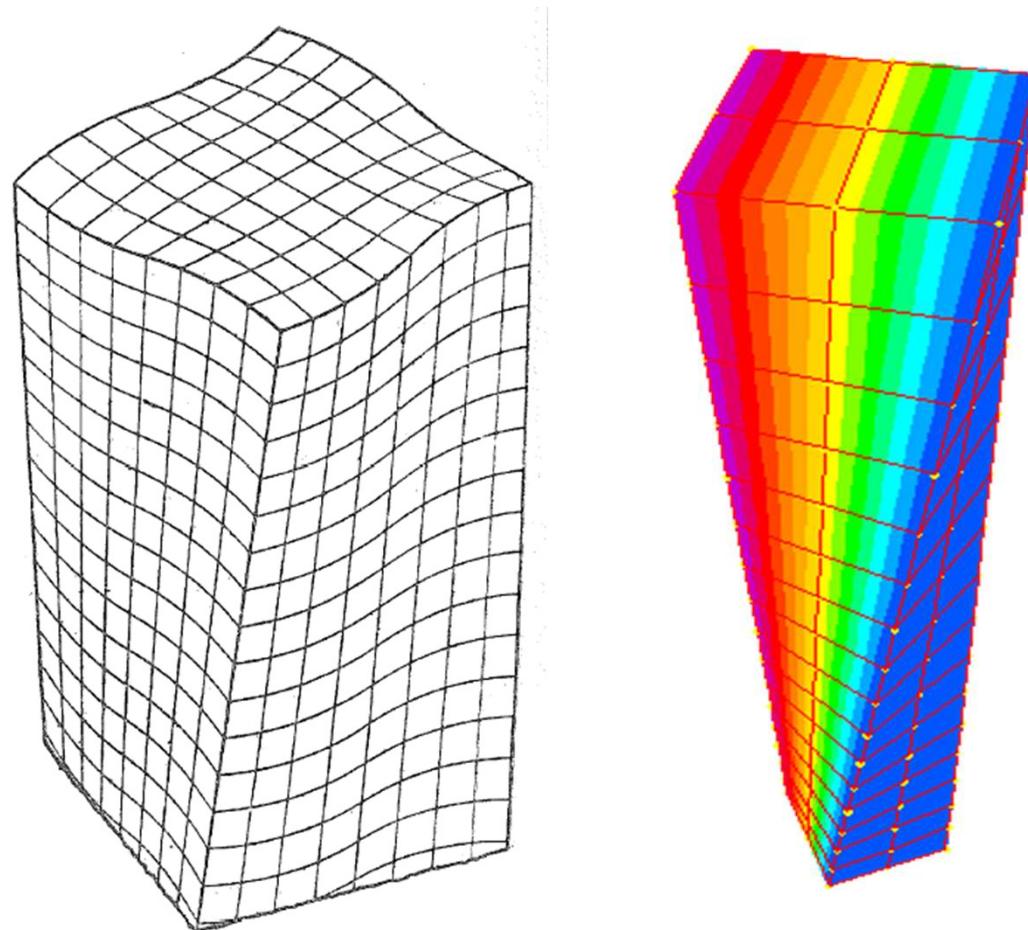


TEORÍA ELASTICIDAD

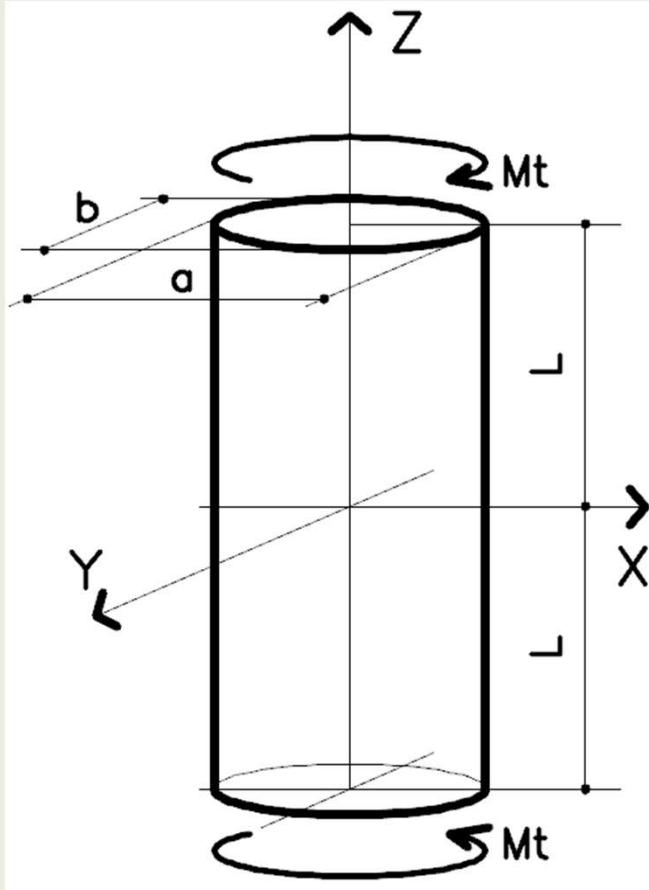
ACTIVIDAD 5 TORSIÓN

Mg. Ing. DANIEL E. LÓPEZ

ANALISIS ESTRUCTURAL II



Barra Sección Elíptica



De la observación del comportamiento

- a. Las secciones giran alrededor del eje de simetría un ángulo variable, 0 en el plano medio y ω en las secciones extremas.
- b. Las secciones no cambian de forma, ni de tamaño.
- c. La generatrices conservan su longitud pero se trasladan verticalmente.

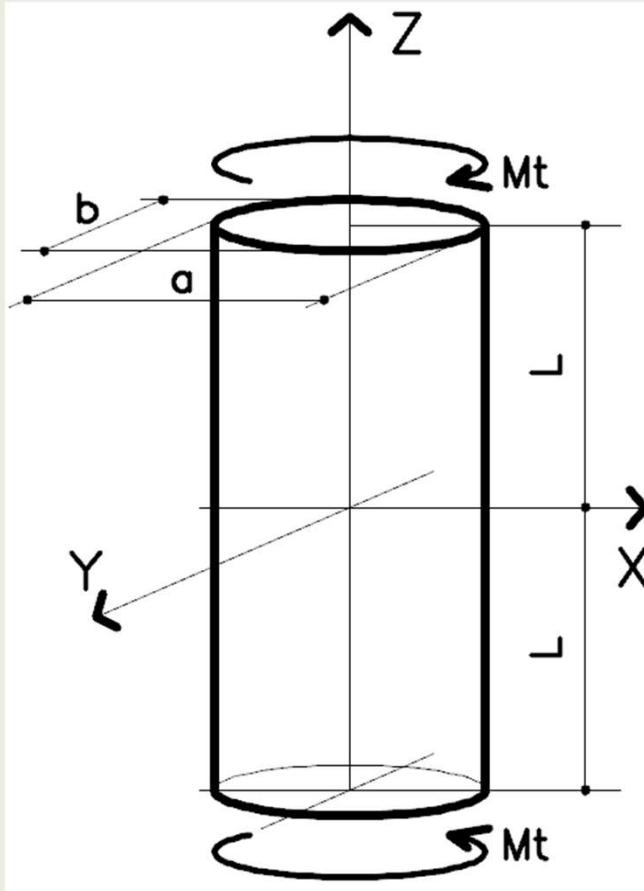
S/a. $\theta = \omega/L$ $u = -\theta z y$ $v = \theta z x$

S/b. $\varepsilon_x = \varepsilon_y = 0$

S/c. $\varepsilon_z = 0$

$w \neq 0 = \theta f(x, y)$

Barra Sección Elíptica



Solución de Saint-Venant

Si existe un función $\phi(x, y)$ tal que:

$$-\frac{\partial \phi}{\partial x} = \tau_{yz} \quad \frac{\partial \phi}{\partial y} = \tau_{xz}$$

será solución del problema si satisface EEI, EEC y EC

EEI (3°Ec)

$$\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} = 0$$

EEC (3°Ec)

$$\tau_{xz} \cos \alpha + \tau_{yz} \cos \beta = 0$$

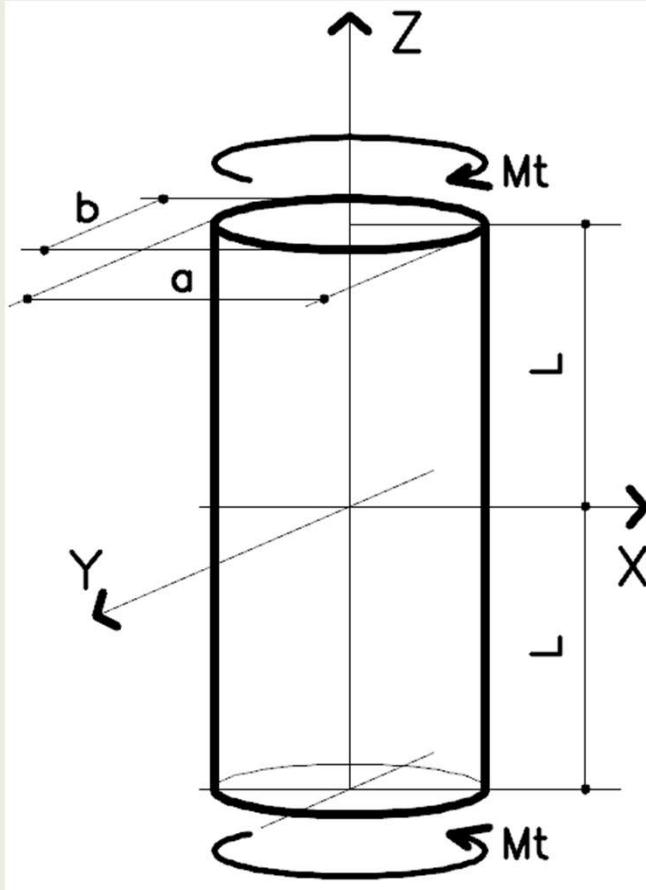
$$\frac{\partial \phi}{\partial y} \cos \alpha - \frac{\partial \phi}{\partial x} \cos \beta = 0$$

$$\frac{\partial \phi}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial \phi}{\partial x} \frac{\partial x}{\partial s} = 0$$

$$\frac{\partial \phi}{\partial s} = 0 \quad \phi = ctte$$

en el Contorno

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Solución de Saint-Venant

EC (2 Ult)

$$\frac{\partial}{\partial y} \nabla^2 \phi(x, y) = 0$$

$$-\frac{\partial}{\partial x} \nabla^2 \phi(x, y) = 0$$

$$\nabla^2 \phi = cte$$

Resumen

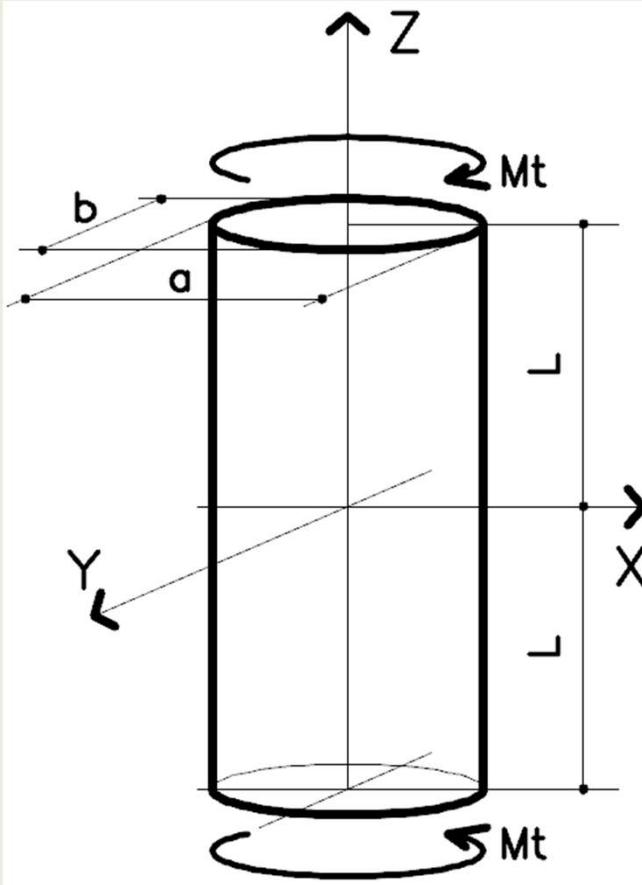
$$-\frac{\partial \phi}{\partial x} = \tau_{yz} \quad \frac{\partial \phi}{\partial y} = \tau_{xz}$$

$$\frac{\partial \tau_{xz}}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} = 0$$

$$\phi = cte \quad \text{en el Contorno}$$

$$\nabla^2 \phi = cte$$

Barra Sección Elíptica



Solución de Saint-Venant

$$\nabla^2 \phi = cte$$

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = -\frac{\partial \tau_{yz}}{\partial x} + \frac{\partial \tau_{xz}}{\partial y} = G \left[-\frac{\partial \gamma_{yz}}{\partial x} + \frac{\partial \gamma_{xz}}{\partial y} \right]$$

reemplazando

$$u = -\theta z y \quad v = \theta z x \quad w = \theta f(x, y)$$

resulta

$$\nabla^2 \phi = -2G \frac{\omega}{L} = -2G\theta$$

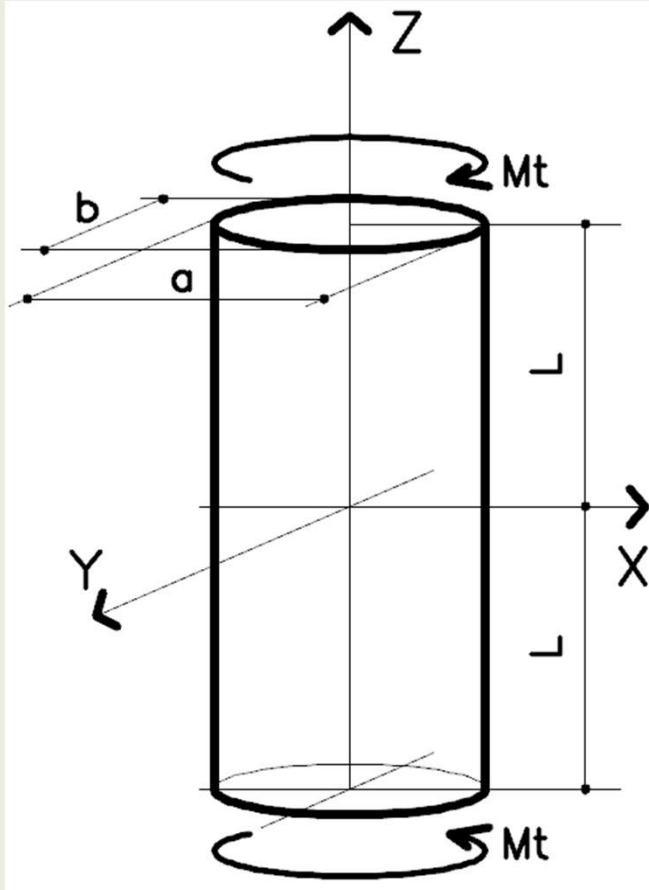
Función ϕ

$$\phi = k \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 \right) \quad \text{Satisface} \quad \frac{\partial \phi}{\partial s} = 0$$

reemplazando

$$2k \left(\frac{1}{a^2} + \frac{1}{b^2} \right) = -2G\theta \quad \rightarrow \quad k = -G\theta \left(\frac{a^2 b^2}{a^2 + b^2} \right)$$

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Solución de Saint-Venant

Función ϕ

$$\phi = -G\theta \left(\frac{a^2 b^2}{a^2 + b^2} \right) \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 \right)$$

Equilibrio M_t

$$M_t = \iint_{\Omega} \tau_{xz} y \, dx dy + \iint_{\Omega} \tau_{yz} x \, dx dy$$

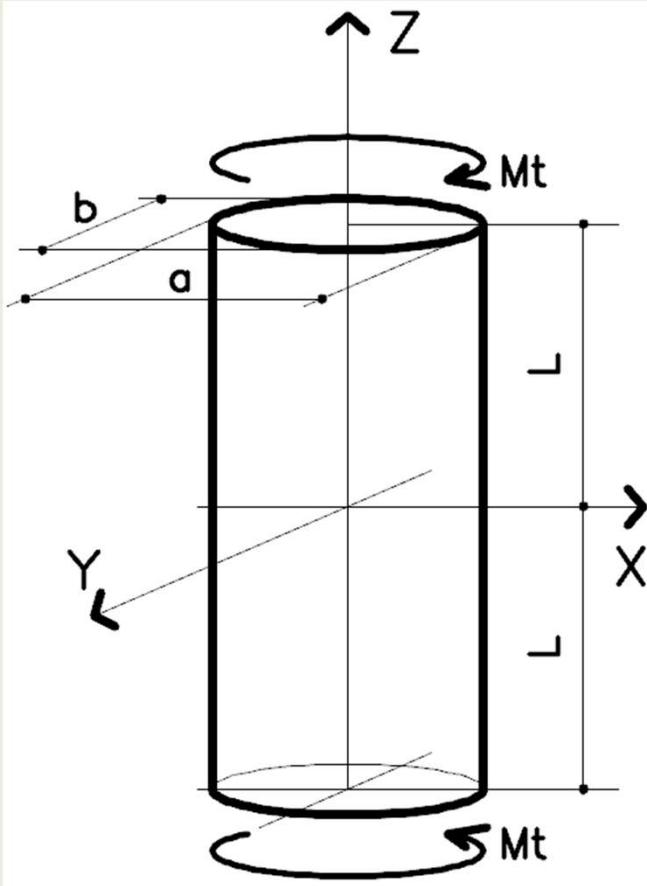
reemplazando $\tau = f(\phi)$

$$M_t = 2 \iint_{\Omega} \phi \, dx dy$$

$$M_t = 2 \iint_{\Omega} -G\theta \left(\frac{a^2 b^2}{a^2 + b^2} \right) \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 \right) \, dx dy$$

$$M_t = \pi G\theta f(a, b) \rightarrow \theta = \dots$$

Barra Sección Elíptica



Solución de Saint-Venant

Cálculo de w

$$\gamma_{xz} = \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}$$

$$\frac{\partial w}{\partial x} = \frac{\tau_{xz}}{G} - \frac{\partial u}{\partial z}$$

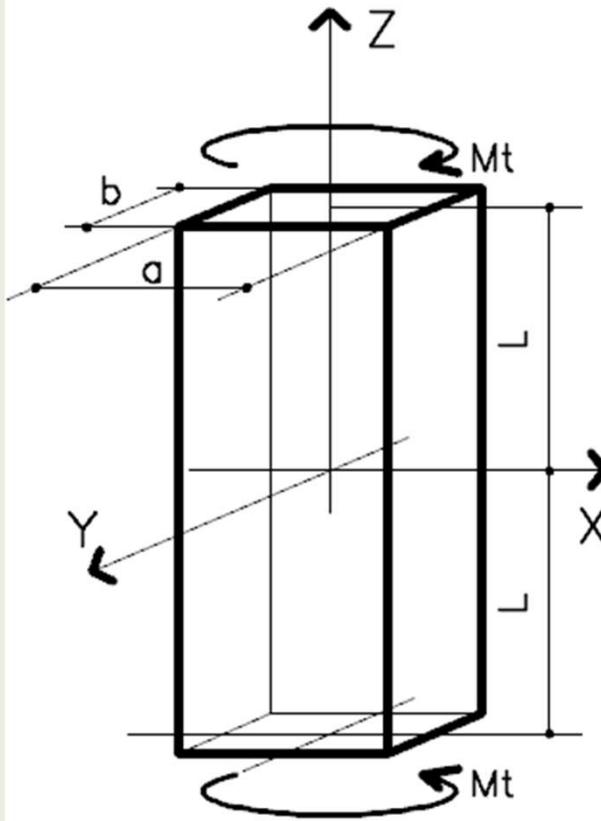
$$\frac{\partial w}{\partial x} = \frac{1}{G} \frac{\partial \phi}{\partial y} + \frac{\omega}{L} y$$

$$w(x) = \int \left(\frac{1}{G} \frac{\partial \phi}{\partial y} + \frac{\omega}{L} y \right) dx \quad \rightarrow \quad w(x) = (\dots)xy + F1(y)$$

$$w(y) = \int \left(\frac{1}{G} \frac{\partial \phi}{\partial x} - \frac{\omega}{L} x \right) dx \quad \rightarrow \quad w(y) = (\dots)xy + F2(x)$$

$$w(x) = w(y) \quad \rightarrow \quad F1(y) = ? \quad F2(x) = ?$$

Barra Sección Rectangular



Diferencias Finitas

| | | |
|---|------------|------------|
| | 2 | |
| 3 | 0 | 1 |
| 4 | | Δz |
| | Δx | |

Cálculo de ϕ

$$(\nabla^2 \phi)_0 = \frac{\phi_1 + \phi_2 + \phi_3 + \phi_4 - 4\phi_0}{\Delta^2} = -2G\theta$$

| | | | |
|---|---|---|---|
| | 5 | 4 | 5 |
| 3 | 2 | 3 | |
| 1 | 0 | 1 | |
| 3 | 2 | 3 | |
| 5 | 4 | 5 | |
| | | | |

$$\phi_1 + \phi_1 + \phi_2 + \phi_2 - 4\phi_0 = -2G\theta\Delta^2$$

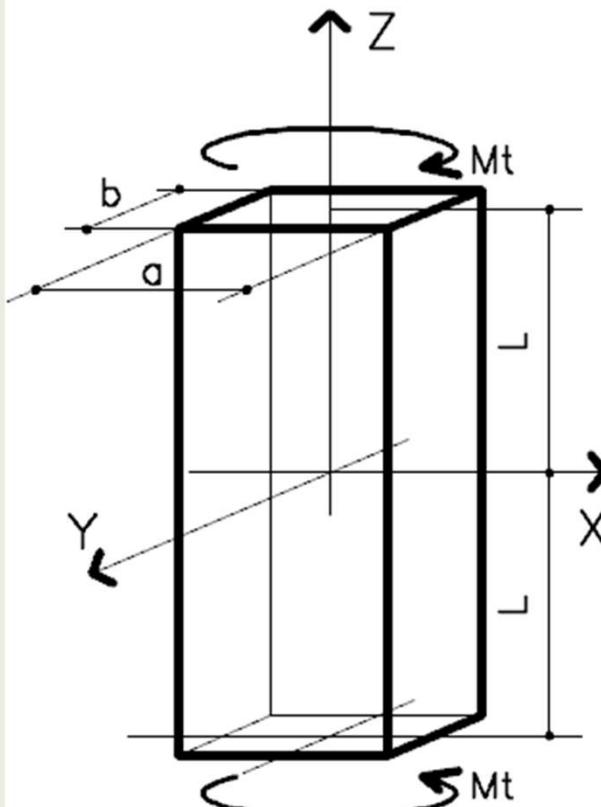
$$2\phi_1 + 2\phi_2 - 4\phi_0 = -2G\theta\Delta^2$$

en n puntos

$$[A][\phi] = -2G\theta\Delta^2[1]$$

$$[\phi] = -2G\theta\Delta^2[A]^{-1}[1]$$

Barra Sección Rectangular



Diferencias Finitas

Cálculo de θ

$$M_t = 2 \iint_{\Omega} \phi \, dxdy$$

$$M_t = 2 \sum \phi \Delta x \Delta y$$

TEORÍA ELASTICIDAD

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Fin

